

Python For Data Science Cheat Sheet

Also see NumPy

SciPy - Linear Algebra

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SciPy

The SciPy library is one of the core packages for scientific computing that provides mathematical algorithms and convenience functions built on the NumPy extension of Python.



Interacting With NumPy

[Also see NumPy](#)

```
>>> import numpy as np  
>>> a = np.array([1,2,3])  
>>> b = np.array([(1+5j,2j,3j), (4j,5j,6j)])  
>>> c = np.array([(1.5,2,3), (4,5,6)], [(3,2,1), (4,5,6)])
```

Index Tricks

```
>>> np.mgrid[0:5,0:5]  
>>> np.ogrid[0:2,0:2]  
>>> np.r_[3,[0]*5,-1:1:10j]  
>>> np.c_[b,c]
```

Create a dense meshgrid
Create an open meshgrid
Stack arrays vertically (row-wise)
Create stacked column-wise arrays

Shape Manipulation

```
>>> np.transpose(b)  
>>> b.flatten()  
>>> np.hstack((b,c))  
>>> np.vstack((a,b))  
>>> np.hsplit(c,2)  
>>> np.vsplit(d,2)
```

Polynomials

```
>>> from numpy import poly1d  
>>> p = poly1d([3,4,5])
```

Create a polynomial object

Vectorizing Functions

```
>>> def myfunc(a):  
...     if a < 0:  
...         return a**2  
...     else:  
...         return a/2  
>>> np.vectorize(myfunc)
```

Vectorize functions

Type Handling

```
>>> np.real(c)  
>>> np.imag(c)  
>>> np.real_if_close(c,tol=1000)  
>>> np.cast['f'](np.pi)
```

Return the real part of the array elements
Return the imaginary part of the array elements
Return a real array if complex parts close to 0
Cast object to a data type

Other Useful Functions

```
>>> np.angle(b,deg=True)  
>>> g = np.linspace(0,np.pi,num=5)  
>>> g[3:] += np.pi  
>>> np.unwrap(g)  
>>> np.logspace(0,10,3)  
>>> np.select([c<4], [c*2])  
  
>>> misc.factorial(a)  
>>> misc.comb(10,3,exact=True)  
>>> misc.central_diff_weights(3)  
>>> misc.derivative(myfunc,1.0)
```

Return the angle of the complex argument
Create an array of evenly spaced values
(number of samples)
Unwrap
Create an array of evenly spaced values (log scale)
Return values from a list of arrays depending on conditions
Factorial
Combine N things taken at k time
Weights for N-point central derivative
Find the n-th derivative of a function at a point

Linear Algebra

You'll use the linalg and sparse modules. Note that `scipy.linalg` contains and expands on `numpy.linalg`.

```
>>> from scipy import linalg, sparse
```

Creating Matrices

```
>>> A = np.matrix(np.random.random((2,2)))  
>>> B = np.asmatrix(b)  
>>> C = np.mat(np.random.random((10,5)))  
>>> D = np.mat([[3,4], [5,6]])
```

Basic Matrix Routines

Inverse

```
>>> A.I  
>>> linalg.inv(A)  
>>> A.T  
>>> A.H  
>>> np.trace(A)
```

Norm

```
>>> linalg.norm(A)  
>>> linalg.norm(A,1)  
>>> linalg.norm(A,np.inf)
```

Rank

```
>>> np.linalg.matrix_rank(C)
```

Determinant

```
>>> linalg.det(A)
```

Solving linear problems

```
>>> linalg.solve(A,b)  
>>> E = np.mat(a).T  
>>> linalg.lstsq(D,E)
```

Generalized inverse

```
>>> linalg.pinv(C)  
>>> linalg.pinv2(C)
```

Creating Sparse Matrices

```
>>> F = np.eye(3, k=1)  
>>> G = np.mat(np.identity(2))  
>>> C[C > 0.5] = 0  
>>> H = sparse.csr_matrix(C)  
>>> I = sparse.csc_matrix(D)  
>>> J = sparse.dok_matrix(A)  
>>> E.todense()  
>>> sparse.isspmatrix_csc(A)
```

Inverse
Inverse
Transpose matrix
Conjugate transposition
Trace

Frobenius norm
L1 norm (max column sum)
L inf norm (max row sum)

Matrix rank

Determinant

Solver for dense matrices
Solver for dense matrices
Least-squares solution to linear matrix equation

Compute the pseudo-inverse of a matrix
(least-squares solver)
Compute the pseudo-inverse of a matrix
(SVD)

Create a 2x2 identity matrix
Create a 2x2 identity matrix

Compressed Sparse Row matrix
Compressed Sparse Column matrix
Dictionary Of Keys matrix
Sparse matrix to full matrix
Identify sparse matrix

Sparse Matrix Routines

Inverse

```
>>> sparse.linalg.inv(I)
```

Norm

```
>>> sparse.linalg.norm(I)
```

Solving linear problems

```
>>> sparse.linalg.spsolve(H,I)
```

Inverse

Norm

Solver for sparse matrices

Sparse Matrix Functions

```
>>> sparse.linalg.expm(I)
```

Sparse matrix exponential

Asking For Help

```
>>> help(scipy.linalg.diagsvd)  
>>> np.info(np.matrix)
```

Matrix Functions

Addition

```
>>> np.add(A,D)
```

Subtraction

```
>>> np.subtract(A,D)
```

Division

```
>>> np.divide(A,D)
```

Multiplication

```
>>> np.multiply(D,A)  
>>> np.dot(A,D)  
>>> np.vdot(A,D)  
>>> np.inner(A,D)  
>>> np.outer(A,D)  
>>> np.tensordot(A,D)  
>>> np.kron(A,D)
```

Exponential Functions

```
>>> linalg.expm(A)  
>>> linalg.expm2(A)  
>>> linalg.expm3(D)
```

Logarithm Function

```
>>> linalg.logm(A)
```

Trigonometric Functions

```
>>> linalg.sinm(D)  
>>> linalg.cosm(D)  
>>> linalg.tanm(A)
```

Hyperbolic Trigonometric Functions

```
>>> linalg.sinhm(D)  
>>> linalg.coshm(D)  
>>> linalg.tanhm(A)
```

Matrix Sign Function

```
>>> np.signm(A)
```

Matrix Square Root

```
>>> linalg.sqrtm(A)
```

Arbitrary Functions

```
>>> linalg.funm(A, lambda x: x*x)
```

Addition

Subtraction

Division

Multiplication
Dot product
Vector dot product
Inner product
Outer product
Tensor dot product
Kronecker product

Matrix exponential
Matrix exponential (Taylor Series)
Matrix exponential (eigenvalue decomposition)

Matrix logarithm

Matrix sine
Matrix cosine
Matrix tangent

Hypberbolic matrix sine
Hyperbolic matrix cosine
Hyperbolic matrix tangent

Matrix sign function

Matrix square root

Evaluate matrix function

Decompositions

Eigenvalues and Eigenvectors

```
>>> la, v = linalg.eig(A)  
  
>>> l1, l2 = la  
>>> v[:,0]  
>>> v[:,1]  
>>> linalg.eigvals(A)
```

Singular Value Decomposition

```
>>> U,s,Vh = linalg.svd(B)  
>>> M,N = B.shape  
>>> Sig = linalg.diagsvd(s,M,N)
```

LU Decomposition

```
>>> P,L,U = linalg.lu(C)
```

Solve ordinary or generalized eigenvalue problem for square matrix
Unpack eigenvalues
First eigenvector
Second eigenvector
Unpack eigenvalues

Singular Value Decomposition (SVD)
Construct sigma matrix in SVD

LU Decomposition

Sparse Matrix Decompositions

```
>>> la, v = sparse.linalg.eigs(F,1)  
>>> sparse.linalg.svds(H, 2)
```

Eigenvalues and eigenvectors
SVD

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